

Class: 11th

Subject: Computer

Unit 3: Algorithms and Problem Solving

❖ Important MCQs:

1. A computational problem differs from a general problem because it:

- (a) Requires human judgment only
- (b) Cannot be solved step-by-step
- (c) Can be solved using an algorithmic process

(d) Has no defined structure

2. Which component ensures that a computational problem produces a meaningful result?

(a) Input only

(b) Output only

(c) Proper transformation of input through process

(d) Random execution

3. In a computational problem, the relationship between input and output is defined by:

(a) Hardware

(b) Algorithm (process)

(c) Storage

(d) User



4. Which of the following best describes the role of an algorithm?

(a) Stores data

(b) Displays output

(c) Transforms input into output through defined steps

(d) Generates random values

5. Identifying inputs, outputs, and processes is important because it:

- (a) Eliminates need for algorithms
- (b) Helps in clearly defining the problem ✓
- (c) Reduces output accuracy
- (d) Avoids computation

6. A problem where multiple valid solutions exist but the best one is required is classified as:

- (a) Decision problem
- (b) Search problem
- (c) Optimization problem ✓
- (d) Counting problem



7. A problem that asks “Is a number prime?” is an example of:

- (a) Search problem
- (b) Decision problem ✓
- (c) Optimization problem
- (d) Counting problem

8. Which scenario best represents a search problem?

-
- (a) Determining even or odd
 - (b) Finding a student with highest marks
 - (c) Finding a specific item that meets criteria ✓
 - (d) Counting total numbers

9. Counting problems differ from search problems because they:

- (a) Find one solution
- (b) Count all possible valid solutions ✓
- (c) Always give yes/no output
- (d) Ignore conditions

10. A well-defined problem guarantees correctness because it:

- (a) Has no process
- (b) Has ambiguous inputs
- (c) Clearly specifies all components (input, process, output) ✓
- (d) Depends on guessing

11. Which issue is most likely to arise in ill-defined problems?

- (a) Fast computation
- (b) Clear solution
- (c) Ambiguity in goals and requirements ✓

(d) Fixed output

12. Why is the example “reducing poverty in Pakistan” considered ill-defined?

(a) It has too many inputs

(b) It lacks clear and precise goals

(c) It has no output

(d) It is computationally simple

13. The effectiveness of solving a computational problem depends mainly on:

(a) Input size only

(b) Output format

(c) Proper definition of all components and process

(d) Hardware speed

14. Which classification focuses on selecting the best possible solution among many?

(a) Decision

(b) Search

(c) Optimization

(d) Counting

15. Which of the following combinations correctly represents a complete computational problem?

- (a) Input + Output only
- (b) Input + Process only
- (c) Process + Output only
- (d) Input + Process + Output

16. Algorithms are important because they:

- (a) Only store data
- (b) Provide logic for solving problems and ensure accuracy
- (c) Replace hardware
- (d) Eliminate input

17. An algorithm can best be described as:

- (a) A random process
- (b) A step-by-step procedure for solving a problem
- (c) A hardware component
- (d) An output device

18. The Generate-and-Test method works by:

- (a) Testing only one solution

(b) Generating and testing possible solutions until a valid one is found



(c) Ignoring incorrect solutions

(d) Using only fixed rules

19. Generate-and-Test method is most suitable when:

(a) Problem space is very large

(b) There is a clear direct solution

(c) Problem space is small and manageable

(d) No solutions exist

20. Heuristics in Generate-and-Test method are used to:

(a) Increase number of solutions

(b) Reduce number of generated solutions and improve efficiency

(c) Eliminate testing phase

(d) Replace algorithms

21. Problem solvability helps to determine:

(a) Hardware performance

(b) Whether a problem can be solved using an algorithm

(c) Input size

(d) Output format

22. A problem is considered solvable if:

(a) It has no input

(b) It can be solved in infinite time

(c) An algorithm can solve it in finite time

(d) It has no output

23. Which feature is common in solvable problems?

(a) Undefined inputs

(b) No procedure

(c) Step-by-step method exists

(d) Random output

24. The Euclidean algorithm is used to:

(a) Sort numbers

(b) Find GCD of two integers

(c) Search data

(d) Count values

25. Unsolvable problems are those that:

(a) Can be solved quickly

(b) Have no algorithm for all cases ✓

(c) Have clear solutions

(d) Require less time

26. The Halting Problem is:

(a) A sorting problem

(b) A solvable problem

(c) An unsolvable problem ✓

(d) A counting problem

27. Who proved the Halting Problem is unsolvable?

(a) Newton

(b) Einstein

(c) Alan Turing ✓

(d) Pascal

28. Tractable problems are those that:

(a) Require infinite time

(b) Can be solved efficiently in polynomial time ✓

(c) Are unsolvable

(d) Have no inputs

29. Polynomial time is associated with:

- (a) Intractable problems
- (b) Efficient computation
- (c) Infinite loops
- (d) Random results

30. Which of the following is a tractable problem?

- (a) Halting Problem
- (b) Traveling Salesman Problem
- (c) Sorting using Merge Sort
- (d) Infinite loop detection

31. Intractable problems are characterized by:

- (a) Polynomial time
- (b) Constant time
- (c) Super-polynomial (often exponential) time
- (d) No computation

32. Traveling Salesman Problem (TSP) is:

- (a) Easily solvable
- (b) Tractable

(c) Intractable (NP-hard)

(d) Decision problem

33. Class P consists of problems that:

(a) Cannot be solved

(b) Are solved efficiently

(c) Are always NP-hard

(d) Have no output

34. Which example belongs to Class P?

(a) Halting Problem

(b) Sorting a list of numbers

(c) TSP

(d) Knapsack Problem

35. Class NP includes problems where:

(a) Solutions cannot be checked

(b) Solutions can be verified quickly

(c) No algorithm exists

(d) Only input matters

36. Sudoku is an example of:

-
- (a) Class P
 - (b) Class NP
 - (c) NP-hard
 - (d) Unsolvable

37. NP-hard problems are:

- (a) Easier than NP
- (b) Exactly same as P
- (c) At least as hard as hardest NP problems
- (d) Always solvable quickly

38. Which of the following is NP-hard?

- (a) Sorting
- (b) Searching
- (c) Traveling Salesman Problem
- (d) Even number check

39. NP-Complete problems are:

- (a) Only in P
- (b) Only unsolvable
- (c) Both in NP and as hard as NP problems

(d) Always easy

40. Which is a classic NP-Complete problem?

(a) Sorting

(b) Searching

(c) Knapsack Problem

(d) GCD calculation

41. Algorithm analysis is used to:

(a) Design hardware

(b) Measure complexity and predict performance

(c) Store data

(d) Generate output

42. Algorithm analysis mainly focuses on:

(a) Input and output

(b) Time and space complexity

(c) Hardware speed

(d) Programming language

43. Time complexity measures:

(a) Memory usage

(b) Running time growth with input size ✓

(c) Output size

(d) Input type

44. Time complexity helps to:

(a) Reduce input

(b) Predict algorithm performance for large data ✓

(c) Eliminate output

(d) Store data

45. Big O notation represents:

(a) Exact running time

(b) Lower bound

(c) Upper bound of running time ✓

(d) Memory usage

46. $O(1)$ time complexity means:

(a) Time increases with input

(b) Constant time regardless of input size ✓

(c) Exponential growth

(d) Linear growth

47. $O(n)$ time complexity indicates:

- (a) Constant growth
- (b) Linear growth with input size
- (c) Quadratic growth
- (d) Logarithmic growth

48. Searching a student in a list of n students is an example of:

- (a) $O(1)$
- (b) $O(\log n)$
- (c) $O(n)$
- (d) $O(n^2)$



StudyNotes360.com

49. $O(n^2)$ time complexity means:

- (a) Linear growth
- (b) Constant growth
- (c) Quadratic growth
- (d) Logarithmic growth

50. Comparing every pair of students is an example of:

- (a) $O(n)$
- (b) $O(\log n)$

(c) $O(n^2)$ ✓

(d) $O(1)$

51. $O(\log n)$ time complexity is associated with:

(a) Linear search

(b) Binary search ✓

(c) Bubble sort

(d) Counting

52. Logarithmic time complexity grows:

(a) Very fast

(b) Very slowly compared to input size ✓

(c) Linearly

(d) Exponentially

53. Space complexity measures:

(a) Execution time

(b) Memory usage with input size ✓

(c) Output accuracy

(d) Input type

54. Space complexity helps to:

(a) Optimize memory usage ✓

(b) Reduce time only

(c) Increase input

(d) Ignore storage

55. Algorithm design refers to:

(a) Writing code only

(b) Creating systematic problem-solving methods ✓

(c) Storing data

(d) Testing output

56. Divide and Conquer works by:

(a) Solving problem randomly

(b) Breaking problem into smaller parts and combining results ✓

(c) Ignoring subproblems

(d) Using only one step

57. Divide and Conquer is effective when:

(a) Problem cannot be divided

(b) Problem can be broken into similar subproblems ✓

(c) No solution exists

(d) Input is small

58. Greedy algorithms make decisions based on:

(a) Global optimum always

(b) Random choice

(c) Locally optimal choices

(d) Backtracking

59. Greedy algorithms are suitable when:

(a) No structure exists

(b) Optimal substructure exists

(c) Only one solution exists

(d) No input given

60. Coin Change problem is an example of:

(a) Divide and Conquer

(b) Greedy algorithm

(c) Backtracking

(d) Sorting

61. Dynamic Programming avoids:

(a) Input

(b) Output

(c) Repeated calculations by storing results ✓

(d) Algorithms

62. Dynamic Programming is useful for:

(a) Independent problems

(b) Overlapping subproblems and optimal substructure ✓

(c) Random problems

(d) Simple problems only

63. Fibonacci sequence is an example of:

(a) Greedy

(b) Dynamic Programming ✓

(c) Backtracking

(d) Sorting

64. Backtracking works by:

(a) Moving forward only

(b) Trying all possibilities and going back on failure ✓

(c) Using greedy approach

(d) Ignoring wrong paths

65. Backtracking is best suited for:

- (a) Simple problems
- (b) Problems with multiple possible solutions (e.g., puzzles) ✓
- (c) Linear problems
- (d) Sorting only

66. Sorting algorithms are used to:

- (a) Search data
- (b) Store data
- (c) Arrange data in order (ascending/descending) ✓
- (d) Delete data

67. Sorting is important because it:

- (a) Removes data
- (b) Replaces algorithms
- (c) Helps in searching and data analysis ✓
- (d) Slows computation

68. Bubble Sort works by:

- (a) Selecting minimum element
- (b) Dividing list into halves

(c) Comparing and swapping adjacent elements

(d) Random selection

69. In Bubble Sort, adjacent elements are:

(a) Ignored

(b) Deleted

(c) Compared and swapped if needed

(d) Stored

70. Bubble Sort is repeated until:

(a) Input ends

(b) List is sorted completely

(c) Output is empty

(d) One element remains

71. Time complexity of Bubble Sort is:

(a) $O(n)$

(b) $O(\log n)$

(c) $O(n^2)$

(d) $O(1)$

72. Selection Sort works by:

(a) Swapping random elements

(b) Selecting smallest/largest element and placing it correctly ✓

(c) Dividing list

(d) Using recursion only

73. In Selection Sort, first step is to:

(a) Reverse list

(b) Find minimum element in unsorted part ✓

(c) Find middle element

(d) Shuffle list

74. Selection Sort has time complexity of:

(a) $O(n)$

(b) $O(n \log n)$

(c) $O(n^2)$ ✓

(d) $O(1)$

75. Which sorting algorithm is best for small datasets?

(a) Merge Sort

(b) Bubble Sort or Selection Sort ✓

(c) Binary Search

(d) BFS

76. Linear Search works by:

(a) Splitting list

(b) Checking each element one by one

(c) Sorting data first

(d) Using recursion

77. Linear Search is used in:

(a) Unsorted lists

(b) Only sorted lists

(c) Graphs only

(d) Trees only

78. Worst-case time complexity of Linear Search is:

(a) $O(1)$

(b) $O(\log n)$

(c) $O(n)$

(d) $O(n^2)$

79. Binary Search requires:

(a) Unsorted data

(b) Sorted data

(c) Graph structure

(d) Random input

80. Binary Search works by:

(a) Checking all elements

(b) Dividing search space into halves

(c) Sorting data

(d) Swapping elements

81. Time complexity of Binary Search is:

(a) $O(n)$

(b) $O(n^2)$

(c) $O(\log n)$

(d) $O(1)$

82. In Binary Search, first step is to check:

(a) First element

(b) Last element

(c) Middle element

(d) Random element

83. BFS is used for:

- (a) Sorting data
- (b) Graph traversal level by level
- (c) Searching arrays
- (d) Multiplying matrices

84. BFS uses which data structure?

- (a) Stack
- (b) Queue
- (c) Tree
- (d) Array only

85. Graph consists of:

- (a) Tables and rows
- (b) Nodes and edges
- (c) Files and folders
- (d) Inputs and outputs

86. BFS explores graph:

- (a) Depth wise
- (b) Randomly



(c) Level by level

(d) Backtracking

87. Binary Search is faster than Linear Search because:

(a) It checks all elements

(b) It divides problem into halves

(c) It uses sorting only

(d) It uses graphs

88. Sorting is often required before:

(a) Deleting data

(b) Searching data efficiently (Binary Search)

(c) Printing output

(d) Input creation

89. Which algorithm is most efficient for searching large sorted data?


(a) Linear Search

(b) Bubble Sort

(c) Binary Search

(d) Selection Sort

90. BFS is mainly used in:

- (a) Sorting problems
- (b) Graph traversal problems 
- (c) Arithmetic problems
- (d) Encryption

❖ Important Short Questions:

1. What is a computational problem?

A computational problem is a problem that can be solved by using a step-by-step procedure (algorithm) that a computer can execute. It involves taking some input, processing it through defined steps, and producing an output.

Example:

Adding two numbers using a program.

Input: 5, 10

Process: $5 + 10$

Output: 15

2. Define algorithm.

An algorithm is a finite set of well-defined step-by-step instructions used to solve a problem. It takes input, processes it in a logical sequence, and produces a result.

Example:

Algorithm to find largest number:

- Start
- Take numbers
- Compare them one by one
- Keep the largest value
- Display result

3. What are input, process, and output in a computational problem?

Input: Data or values given to the algorithm before processing

Process: Steps or rules applied to input

Output: Final result after processing

Example:

To add two numbers:

- Input = 3 and 7
- Process = $3 + 7$
- Output = 10

4. What is the purpose of characterizing a computational problem?

Characterizing a computational problem means clearly identifying its inputs, outputs, and process. The purpose is to understand the problem properly so that it can be solved efficiently using an algorithm.

Example:

To check even number:

- Input = number
- Process = divide by 2 and check remainder
- Output = even or odd

5. Define decision problem.

A decision problem is a type of problem where the output is only in Yes or No form. It does not give detailed results, only a decision.

Example:

Is 9 a prime number?

Answer: No

6. Define search problem.

A search problem is a problem in which we need to find a specific item or solution from a set of possible options that satisfies given conditions.

Example:

Finding a student with the highest marks in a class list.

7. What is an optimization problem?

An optimization problem is a problem where the goal is to find the best possible solution among many possible solutions based on some criteria like minimum cost or maximum profit.

Example:

Finding the shortest route between two cities.

8. What is a counting problem?

A counting problem involves finding the total number of possible solutions that satisfy certain conditions.

Example:

How many ways 3 students can be arranged in a row?

Answer: 6 ways

9. Differentiate between well-defined and ill-defined problems.

Well-defined problems: Have clear inputs, processes, and outputs. They are easy to solve using algorithms.

Ill-defined problems: Have unclear goals and vague requirements, making them difficult to solve computationally.

Example:

- **Well-defined:** Check if a number is even
- **Ill-defined:** How to reduce poverty in Pakistan

10. Give an example of a well-defined problem.

A well-defined problem has a clear structure and exact solution steps.

Example:

Checking whether a number is even or odd.

Input: 6

Process: $6 \div 2$ remainder check

Output: Even number

11. Give an example of an ill-defined problem.

An ill-defined problem is one that has unclear goals and vague requirements, so it cannot be solved using a fixed algorithm.

Example:

“How to reduce poverty in Pakistan”

This is ill-defined because there is no single clear method, input, or exact output. It depends on many uncertain factors like economy, education, and policies.

12. What is the Generate-and-Test method?

Generate-and-Test is a problem-solving method where we generate possible solutions one by one and test each solution to see whether it satisfies the required conditions. This process continues until a correct solution is found or all possibilities are checked.

Example:

Solving a password problem by trying different combinations until the correct one is found.

13. In which situations is Generate-and-Test method useful?

This method is useful when:

- The problem space is small
- There is no clear direct method to find solution
- Exhaustive search is possible
- Heuristics can reduce unnecessary solutions

Example:

Solving simple puzzles or small search problems where all possibilities can be tested.

14. What is algorithm analysis?

Algorithm analysis is the process of studying an algorithm to determine its efficiency in terms of time and space (memory usage). It helps us understand how well an algorithm performs when the input size increases.

Example:

Comparing Bubble Sort and Merge Sort to see which is faster for large datasets.

15. Define time complexity.

Time complexity is a measure of how the running time of an algorithm increases as the input size increases. It helps in evaluating algorithm efficiency.

Example:

If sorting 10 numbers takes 1 second, sorting 100 numbers will take more time depending on algorithm type.

16. What is Big O notation?

Big O notation is a mathematical way to describe the upper bound of an algorithm's time complexity. It shows how the running time increases with input size and helps compare different algorithms.

Example:

$O(n)$, $O(\log n)$, $O(n^2)$

17. What does $O(1)$ time complexity represent?

$O(1)$ means constant time complexity, where the running time does not change with input size.

Example:

- Accessing a specific element in an array using index.
- No matter how large the array is, time remains constant.

18. What is $O(n)$ time complexity?

$O(n)$ means linear time complexity, where the running time increases directly with input size.

Example:

- Searching an element in an unsorted list (Linear Search).
- If list size increases, time also increases proportionally.

19. What is $O(n^2)$ time complexity?

$O(n^2)$ means quadratic time complexity, where the running time increases with the square of input size. It happens when each element is compared with every other element.

Example:

- Bubble Sort or Selection Sort.
- If 5 elements take some time, 10 elements take much more time due to repeated comparisons.

20. What is $O(\log n)$ time complexity?

$O(\log n)$ means logarithmic time complexity, where the problem size is reduced by half at each step, making it very efficient for large datasets.

Example:

Binary Search.

If we search a number in a sorted list, we keep dividing the list into halves until we find the target.

21. Define space complexity.

Space complexity is the measure of how much memory (space) an algorithm uses as the input size increases. It includes memory required for input data, temporary variables, and processing.

Example:

If an algorithm stores a list of 100 numbers, it uses more memory than storing 10 numbers.

22. What is the purpose of space complexity analysis?

The purpose of space complexity analysis is to determine how efficiently an algorithm uses memory resources, especially when dealing with large datasets. It helps in choosing algorithms that do not consume excessive memory.

Example:

Comparing two algorithms where one uses extra arrays and the other does not.

23. What is Divide and Conquer technique?

Divide and Conquer is an algorithm design technique in which a problem is:

- Divided into smaller subproblems
- Solved independently
- Combined to get final solution

Example:

Merge Sort divides a list into halves, sorts them separately, and then merges them.

24. Define greedy algorithm.

A greedy algorithm is a method where we make the best possible choice at each step (locally optimal choice) with the hope of finding a global optimal solution.

Example:

Coin Change problem — selecting the largest coin first to make change.

25. What is dynamic programming?

Dynamic Programming (DP) is a technique used to solve problems by breaking them into smaller overlapping subproblems and storing their results to avoid repeated calculations.

Example:

Fibonacci sequence where previous results are stored instead of recalculating.

26. What is backtracking?

Backtracking is a problem-solving technique where we build a solution step by step, and if a step does not lead to a correct solution, we go back and try another option.

Example:

Solving a maze or puzzle by trying different paths and returning when a path fails.

27. What is Bubble Sort?

Bubble Sort is a simple sorting algorithm that repeatedly compares adjacent elements and swaps them if they are in the wrong order until the list is sorted.

Example:

[5, 3, 8, 4] → after sorting → [3, 4, 5, 8]

28. What is Selection Sort?

Selection Sort is a sorting technique where we repeatedly find the smallest element from the unsorted part and place it at the beginning.

Example:

[29, 10, 14] → smallest is 10 → swap → [10, 29, 14]

29. What is Linear Search and where is it used?

Linear Search is a searching method where we check each element one by one until the required element is found.

It is used in unsorted or small datasets.

Example:

Searching “Islamabad” in a list of city names by checking each one sequentially.

30. What is Binary Search and why is it more efficient than Linear Search?

Binary Search is an efficient searching algorithm that works on sorted data. It repeatedly divides the search space into two halves and eliminates one half each time.

It is more efficient than Linear Search because it reduces the number of comparisons significantly, using $O(\log n)$ time instead of $O(n)$.

Example:

Searching a number in [1, 3, 5, 7, 9] by repeatedly checking the middle element.

❖ Important Long Questions

🌟 **Q1. Explain computational problems and their main components in detail.**

Answer:

A computational problem is a problem that can be solved using a step-by-step logical procedure called an algorithm, which can be executed by a computer. In simple words, it is a problem where we clearly define what we need to solve and then use a structured method to get the solution.

Computational problems are the foundation of computer science because every program or software is designed to solve some type of computational problem.

◆ **Main Components of a Computational Problem**

A computational problem has three basic and very important components:

1. Input

Input refers to the data or information given to the algorithm before processing begins. It is the starting point of any computational problem.

- Input can be numbers, text, or any form of data.
- Without input, no problem can be solved.

Example:

If we want to add two numbers, say 5 and 10, then:

Input = 5 and 10

2. Process

Process refers to the set of step-by-step instructions (algorithm) that are applied to the input to solve the problem.

- It is the logic or method used to transform input into output.
- It defines how the problem is solved.

Example:

To add two numbers:

Process = $5 + 10$

In real programming, this process is written as an algorithm or code.

3. Output

Output is the final result obtained after applying the process on input data.

- It is the solution to the problem.
- It is the goal of the computational process.

Example:

Input = 5 and 10

Process = addition

Output = 15

Complete Example of a Computational Problem

Let's understand all components together:

Problem: Find whether a number is even or odd.

- Input: A number (e.g., 8)
- Process: Check if number is divisible by 2
- Output: Even or Odd

So:

$8 \div 2 = 4$ (no remainder) \rightarrow Output = Even

Importance of Computational Problems

- They help in solving real-world problems systematically
- They allow computers to perform accurate and fast calculations
- They form the basis of all algorithms and programming

Summary:

A computational problem is completely defined when we clearly specify input, process, and output. These three components ensure that a problem can be solved logically and efficiently using a computer algorithm.

★ Q2. Explain classification of computational problems with examples.

Answer:

Computational problems are classified into different types based on the nature of the output and the goal of the problem. This classification helps in selecting the correct algorithm to solve the problem efficiently.

The main types of computational problems are:

1. Decision Problems

A decision problem is a type of problem in which the output is always a simple Yes or No answer. It only checks whether a condition is true or false.

These problems do not provide a detailed solution; they only give a decision.

Example:

- Is 11 a prime number? → Yes
- Is 8 an odd number? → No

Explanation:

The computer only decides whether the statement is correct or not.

2. Search Problems

A search problem is a problem where the goal is to find a specific element or solution from a given set of data that satisfies certain conditions.

In this type, we do not just answer yes or no; instead, we actually locate the required item.

Example:

- Finding the student with the highest marks in a class
- Searching for a contact name in a phone list

Explanation:

The algorithm searches through data until the required result is found.

3. Optimization Problems

An optimization problem is a problem where the goal is to find the best possible solution among many possible solutions according to a given condition such as minimum cost or maximum profit.

These problems involve comparing multiple solutions and selecting the most efficient one.

Example:

- Finding the shortest route between two cities
- Minimizing travel cost in a transport system

Explanation:

The algorithm evaluates different possibilities and selects the best one.

4. Counting Problems

A counting problem is a type of problem where the goal is to count how many possible solutions satisfy certain conditions.

Instead of finding one solution, we calculate the total number of valid outcomes.

Example:

- Counting how many ways 3 students can be arranged in a line
- Counting number of valid combinations of passwords

Explanation:

The algorithm focuses on counting all possible valid solutions.

Summary:

Computational problems are classified into decision, search, optimization, and counting problems. Each type has a different purpose and requires a different algorithmic approach. This classification is very important in computer science because it helps in solving problems efficiently and correctly.

✓ Exam Tip:

Always remember:

Decision = Yes/No

Search = Find item

Optimization = Best result

Counting = Number of solutions

★ Q3. Explain Big O notation and time complexity with examples.

Answer:

Big O notation and time complexity are very important concepts in computer science used to measure and compare the efficiency of algorithms.

Time Complexity

Time complexity refers to the amount of time an algorithm takes to complete its execution based on the input size (n). It shows how the running time of an algorithm increases when the input data becomes larger.

In simple words, it helps us understand whether an algorithm is fast or slow when working with large amounts of data.

Example:

- If sorting 10 numbers takes less time, but sorting 10,000 numbers takes much more time, then time complexity helps us describe this growth.

Big O Notation

Big O notation is a mathematical way to describe the performance of an algorithm, especially its time complexity. It represents the upper bound (worst-case performance) of an algorithm.

It is used to compare different algorithms and decide which one is more efficient.

Types of Time Complexity with Examples

1. $O(1)$ – Constant Time

In constant time complexity, the running time of the algorithm does not change with input size. It always takes the same amount of time.

Example:

-
- Accessing an element in an array using its index.
 - Even if the array has 10 elements or 10,000 elements, accessing one specific element takes the same time.

2. $O(n)$ - Linear Time

In linear time complexity, the running time increases directly with the input size. If input doubles, time also doubles.

Example:

- Linear Search, where we check each element one by one until we find the required value.
- If there are 100 elements, we may need up to 100 checks.

3. $O(n^2)$ - Quadratic Time

In quadratic time complexity, the running time increases with the square of the input size. This usually happens when there are nested loops.

Example:

- Bubble Sort, where each element is compared with every other element.
- If there are 5 elements, comparisons are small, but if there are 100 elements, comparisons increase a lot.

4. $O(\log n)$ - Logarithmic Time

In logarithmic time complexity, the problem size is reduced by half in each step, making it very efficient for large datasets.

Example:

- Binary Search, where we repeatedly divide a sorted list into two halves to find an element.
- If we search in a list of 1000 elements, we eliminate half of the data in each step.

Importance of Big O Notation

- Helps in comparing different algorithms
- Shows how an algorithm behaves with large input
- Helps in choosing the most efficient solution
- Focuses on worst-case performance

Summary:

Big O notation is a standard way to measure time complexity. It helps us understand how efficiently an algorithm works as input size increases. Different complexities like $O(1)$, $O(n)$, $O(n^2)$, and $O(\log n)$ describe how fast or slow an algorithm is.

🌟 Q4. Explain algorithm design techniques with examples.

Answer:

Algorithm design techniques are systematic methods used to design efficient algorithms to solve computational problems. These techniques

help programmers break complex problems into simpler parts and solve them in an organized way.

The main algorithm design techniques include Divide and Conquer, Greedy Algorithms, Dynamic Programming, and Backtracking.

1. Divide and Conquer

Divide and Conquer is a technique in which a large problem is divided into smaller subproblems, each subproblem is solved separately, and then their solutions are combined to get the final result.

This method is useful when a problem can be broken into similar smaller problems.

Example:

- Merge Sort is a classic example.
- The list is divided into two halves
- Each half is sorted separately
- Then both halves are merged into a sorted list

2. Greedy Algorithm

A greedy algorithm works by making the best possible choice at each step (locally optimal choice) with the hope that these choices will lead to a global optimal solution.

It does not reconsider previous decisions.

Example:

Coin Change Problem

- Always select the largest coin first
- Then move to smaller coins
- This helps in reducing the total number of coins used.

3. Dynamic Programming

Dynamic Programming (DP) is an optimization technique where a problem is solved by breaking it into smaller overlapping subproblems, and the results of these subproblems are stored to avoid repeated calculations.

This improves efficiency by saving previous results.

Example:

Fibonacci sequence

Instead of recalculating values again and again, previously calculated values are stored and reused.

4. Backtracking

Backtracking is a technique where we try to build a solution step by step, and if a step does not lead to a valid solution, we go back (backtrack) and try another option.

It is used when we need to explore all possible solutions.

Example:

Maze solving or puzzle solving

- Try a path
- If it fails, go back and try another path

Comparison of Techniques (Conceptual Understanding)

- **Divide and Conquer:** Break problem into independent parts
- **Greedy:** Make best choice at each step
- **Dynamic Programming:** Store results of subproblems
- **Backtracking:** Try all possibilities and backtrack if needed

Summary:

Algorithm design techniques are essential for solving problems efficiently. Each technique is suitable for different types of problems and helps in improving performance, reducing complexity, and finding correct solutions.

🌟 **Q5. Explain sorting and searching algorithms with their working and complexity.**

Answer:

Sorting and searching algorithms are fundamental in computer science. They are widely used to organize data and retrieve information efficiently from large datasets.

A) Sorting Algorithms

Sorting algorithms are used to arrange data in a specific order, such as ascending or descending. Sorting is often required before performing advanced operations like searching or analysis.

1. Bubble Sort

Bubble Sort is a simple sorting algorithm that works by repeatedly comparing adjacent elements and swapping them if they are in the wrong order.

Working:

- Start from the first element
- Compare adjacent elements
- Swap if they are in wrong order
- Repeat until no swaps are needed

Example:

[5, 3, 8, 4]

→ [3, 5, 8, 4]

→ [3, 5, 4, 8]

→ [3, 4, 5, 8]

Time Complexity:

$O(n^2)$

2. Selection Sort

Selection Sort works by finding the smallest element from the unsorted part and placing it at the beginning.

Working:

- Find minimum element
- Swap it with first unsorted element
- Move boundary forward
- Repeat process

Example:

[29, 10, 14]

→ [10, 29, 14]

→ [10, 14, 29]

Time Complexity:

$O(n^2)$

B) Searching Algorithms

Searching algorithms are used to find a specific element in a dataset.

1. Linear Search

Linear Search checks each element one by one until the required element is found.

Working:

-
- Start from first element
 - Compare each element with target
 - Continue until found or list ends

Example:

List: [Karachi, Lahore, Islamabad]

Search: Islamabad

→ Check Karachi ❌

→ Check Lahore ❌

→ Found Islamabad ✓

Time Complexity:

$O(n)$

Use Case:

Used in unsorted or small datasets

2. Binary Search

Binary Search works on sorted data only and repeatedly divides the search space into half.

Working:

- Check middle element
- If target is smaller → search left half

-
- If target is larger → search right half
 - Repeat until found

Example:

[1, 3, 5, 7, 9]

Search: 7

→ Check middle → found immediately

Time Complexity:

$O(\log n)$

Use Case:

Used in large sorted datasets

Comparison of Searching Algorithms (Conceptual)

- **Linear Search:** checks one by one
- **Binary Search:** divides data into halves

Binary Search is more efficient because it reduces comparisons significantly.

Summary:

Sorting algorithms (Bubble Sort, Selection Sort) help organize data, while searching algorithms (Linear Search, Binary Search) help retrieve data efficiently. Their performance is measured using time complexity,

where Binary Search is the most efficient among the discussed methods.

Note:

This chapter is designed to provide a solid foundation of knowledge, with the goal of deepening understanding and encouraging further exploration of the subject. The content has been carefully selected to support effective learning and inspire students to engage with the topic more deeply.

Author: Muhammad Asghar

Purpose: To contribute to education by offering insightful, valuable content that enhances learning and understanding.

Copyright & Usage Policy

© 2026 **Studynotes360.com**. All Rights Reserved.

No part of these notes may be reproduced, redistributed, or used for commercial purposes without explicit written permission from the author. These notes are intended solely for personal study and educational use.